





## RB-EKEN 16

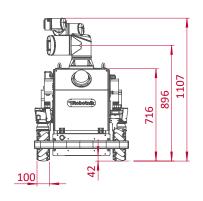
# COMPLETELY INTEGRATED COLLABORATIVE MOBILE MANIPULATOR (CMM) FOR INDUSTRIAL TASKS

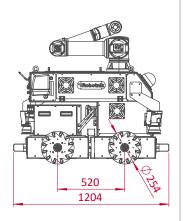
INDUSTRIAL MOBILE MANIPULATION

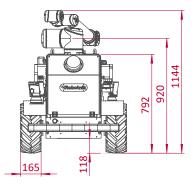
PICK & PLACE LOADING / UNLOADING POSITIONING OF WORKPIECES ASSEMBLY SCREWING DRILLING / MILLING INSPECTION AND CHECK \*\*Robotnik Robotnik

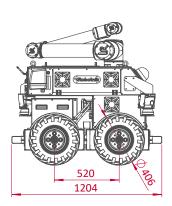
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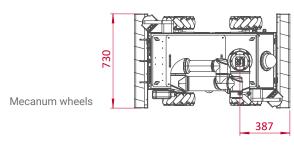


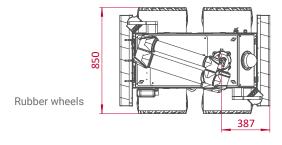












#### TECHNICAL SPECIFICATIONS

#### **MECHANICAL**

Dimensions **1.204 x 730 x 1.107 mm (Folded)** 

(mecanum wheels)

Weight 284 kg

Payload 300 kg

Speed 2 m/s

Environment Indoor/Outdoor

Autonomy 4 h continuous motion

Batteries **LiFePO<sub>4</sub> 60Ah@48V** 

Motors 4 x 1,2 kW

Temperature range 0° to +40°C

Max. slope 60 % (with outdoor wheels)

#### CONTROL

Controller **Open architecture ROS** 

**Integrated PC with Linux** 

Communication WiFi 802.11n

Connectivity RJ45, USB, HDMI

#### ARM

Weight 33,1 kg

Payload 16 kg

Reach 900 mm