



## **RB-ROBOUT+**

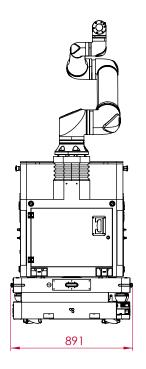
MOBILE MANIPULATOR ROBOT (MMR)

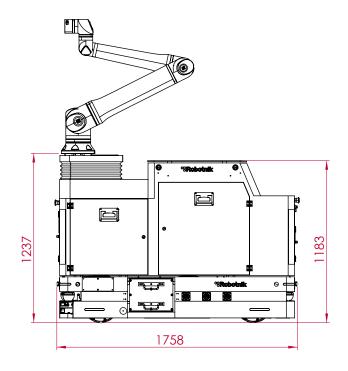
AUTONOMOUS AND
COLLABORATIVE MOBILE
MANIPULATOR ROBOT (MMR)
FOR LONG REACH AND HEAVY
PAYLOADS

# **TOOL OPERATIONS ON LARGE PARTS:** MASKING POLISHING CLEANING SCREW TIGHTENING \*\*Robotnik \*:Robotnik

### **RB-ROBOUT+**







#### TECHNICAL SPECIFICATIONS

#### MECHANICAL

Dimensions 1.758 x 891 x 1.237 mm

Weight 650 kg

Mobile base payload 500 kg

Arm payload 20 kg

UR20 - Arm reach 1.750 mm

Speed 1,1 m/s

Autonomy Up to 10 h

Traction motors 3 kw with break

Environment Indoor

Enclosure class (IP) IP42 / Weatherproof

Temperature range 0° to + 50°C

Traction system **Omnidirectional** 

Localization system **SLAM | Magnetic guide** 

Battery LiFePO<sub>4</sub> 100Ah@48V

Anchor points 4 on the top

Max. slope 13%

#### CONTROL

Controller Open architecture ROS

**Integrated CPU with Linux** 

Communication WiFi 02.11a/b/g/n/ac

Bluetooth 5.1 (5G/4G optional)

Connectivity USB, RJ45, HDMI, power supply

12, 24 VDC and batteries

Robot safety Safety laser (2x)

**Safety PLC** 

Safety button (4x)

#### OPTIONS

**Roller conveyor** 

Plug and play integration of Universal Robots ™ OEM DC

e-series arms

**Telescopic column from 500 to** 

1.400 mm

Conformity CE following ISO 3691-4 and ISO 13482. \*

Collision avoidance triggered by a person or other obstacle while driving.